

# Robust Estimation of the Parameters of the GPD

## A Case Study

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# Agenda

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2 Background

3 Casestudy

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# Introduction

- Models are approximations to reality.
- Classical parametric statistics do not provide information on behavior of procedures if model assumptions are just approximately valid.
- Robust statistics describes the behavior of statistical procedures in the neighborhood of strict model assumptions and introduce procedures that are more resilient to deviations from the ideal setup.

## Accuracy of Stellar Movements

1914 Eddington proposes mean absolute deviations.

$$\sigma_1 = \frac{1}{n} \sqrt{\frac{\pi}{2}} \sum_{i=1}^n |x_i - \bar{x}|, \quad \text{s.e. } \sigma_1 = \frac{\sigma}{\sqrt{2n}} \sqrt{\pi - 2}$$

1920 Fisher comments that the mean square error is 12% more efficient.

$$\sigma_2 = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2, \quad \text{s.e. } \sigma_2 = \frac{\sigma}{\sqrt{2n}}$$

1960 Tukey points out that the mean absolute deviations may be more efficient under slight contamination.

$$F = (1 - \varepsilon) \Phi(x/\sigma) + \varepsilon \Phi(x/(3\sigma))$$



## Smooth Parametric Model

Family  $\mathcal{P}$  of generalized Pareto distributions (GPD) with df

$$F_{\theta}(x) = 1 - \left(1 + \xi \frac{x}{\beta}\right)^{-1/\xi}$$

on sample space  $\mathcal{X} = [0, \infty)$  and unknown parameter  $\theta = (\beta, \xi) \in (0, \infty) \times [0, \infty)$ .

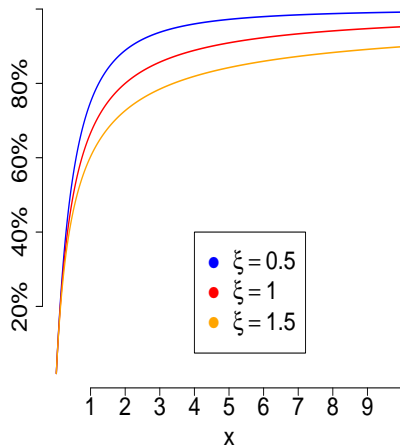
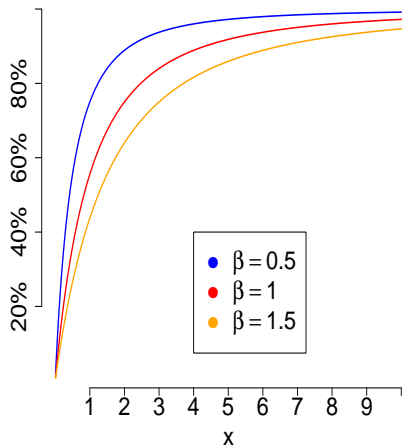
$\mathcal{P}$  is  $L_2$ -differentiable (smooth) at  $\theta \in \Theta$  with  $L_2$ -derivative (scores function)

$$\Lambda_{\theta}(x) = \frac{d}{d\theta} \ln f_{\theta}(x),$$

$E_{\theta} \Lambda_{\theta} = 0$  and Fisher information of full rank  $\mathcal{I}_{\theta} = E_{\theta} \Lambda_{\theta} \Lambda_{\theta}^t > 0$ .

## GPD with different Scale and Shape Parameters $\beta$ and $\xi$

The shape parameter (tail index)  $\xi$  determines essentially the tail of the df.



## Influence Curves and Asymptotically Linear Estimators

The set  $\Psi_2(\theta)$  of all square integrable influence curves at  $P_\theta$  is

$$\Psi_2(\theta) = \left\{ \psi_\theta \in L_2^k(P_\theta) \mid E_\theta \psi_\theta = 0, E_\theta \psi_\theta \Lambda_\theta^t = \mathbb{I}_k \right\}.$$

Estimator  $\hat{\theta}_n$  is called asymptotically linear at  $P_\theta$  if there is an influence curve  $\psi_\theta$  with

$$\sqrt{n}(\hat{\theta}_n - \theta) = \frac{1}{\sqrt{n}} \sum_{i=1}^n \psi_\theta(X_i) + o_{P_\theta^n}(n^0).$$

### Example

Let  $\hat{\theta}_n^{ML}$  be the ML estimator for  $\theta$ . The influence curve is given by

$$\psi_\theta(x) = \mathcal{J}_\theta^{-1} \Lambda_\theta(x).$$

## Generalization of ML Calculus

### Estimation Problem

Observations  $X_1, \dots, X_n$  i.i.d.,  $X_i \sim P_\theta$  for some  $\theta \in \Theta$ .

Estimator  $\hat{\theta}_n = \hat{\theta}_n(X_1, \dots, X_n)$  for  $\theta$ .

### Maximum Likelihood Estimator $\hat{\theta}_n^{ML}$

$$L_n(\theta) = \frac{1}{n} \sum_{i=1}^n \ln f_\theta(X_i) = \max_{\theta} \quad \text{or} \quad l_n(\theta) = \frac{1}{n} \sum_{i=1}^n \Lambda_\theta(X_i) = 0.$$

Substitute sensitive scores function  $\Lambda_\theta = (\partial/\partial\theta) \ln f_\theta$  by more robust function  $\Psi_\theta$ .

### M Estimator $\hat{\theta}_n^M$

$$M_n(\theta) = \frac{1}{n} \sum_{i=1}^n m_\theta(X_i) = \max_{\theta} \quad \text{or} \quad \psi_n(\theta) = \frac{1}{n} \sum_{i=1}^n \Psi_\theta(X_i) = 0.$$



## Examples for Scores Functions

Observations  $X_1, \dots, X_n$  i.i.d.,  $X_i \sim \text{Exp}(\theta)$  with  $f_\theta(x) = \theta e^{-\theta x}$ ,  $\theta \in (0, \infty)$ .

$L_2$ -derivative  $\Lambda_\theta(x) = \frac{\partial}{\partial \theta} \ln f_\theta(x) = \frac{1}{\theta} - x$ .

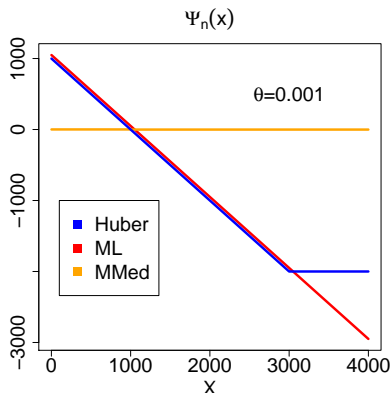
Scores functions to estimate  $\theta$

$$\Psi_n^{ML}(x) = \Lambda_\theta(x).$$

$$\Psi_n^{MMed}(x) = \text{sgn}(\Lambda_\theta(x)).$$

$$\Psi_n^{\text{Huber},c}(x) = \begin{cases} c & \text{if } \Lambda_\theta(x) > c \\ \Lambda_\theta(x) & \text{if } |\Lambda_\theta(x)| \leq c \\ -c & \text{if } \Lambda_\theta(x) < -c \end{cases}$$

$$= \min\left(1, \frac{c}{|\Lambda_\theta(x)|}\right) \Lambda_\theta(x).$$



## Neighborhood and Criteria to assess an Estimator

Observations  $X_i \sim Q$  with  $Q$  in neighborhood of  $P_\theta$ .

(Contamination) Neighborhood of  $P_\theta$  as convex combination

$$B_c(P_\theta, r) = \left\{ (1-r)^+ P_\theta + \min(1, r) Q \mid Q \in \mathcal{M}^1(\mathcal{A}) \right\}$$



Criteria for efficiency and (local) robustness of an estimator

- i. Trace of asymptotic covariance:  $\text{trace Cov}_\theta \psi_\theta = E_\theta \|\psi_\theta\|^2$
- ii. Gross error sensitivity (GES):  $\sup_x \|\psi_\theta(x)\|$

Robust optimization problem

$$\text{(ROP1)} \quad E_\theta \|\psi_\theta\|^2 = \min! \quad \text{subject to} \quad \sup_x \|\psi_\theta(x)\| \leq b$$

$$\text{(ROP2)} \quad \max \text{MSE}_\theta(\psi_\theta, r) := E_\theta \|\psi_\theta\|^2 + r^2 \sup_x \|\psi_\theta(x)\|^2 = \min!$$

## Estimators

Estimator

Solution to

Maximum likelihood estimator (MLE)

$$\frac{1}{n} \sum_{i=1}^n \Lambda_{\theta}(X_i) = 0$$

Method of medians estimator (MMed)

$$\frac{1}{n} \sum_{i=1}^n \operatorname{sgn}(\Lambda_{\theta}(X_i) - a_{\theta}) = 0$$

under constraint  $E_{\theta}[\operatorname{sgn}(\Lambda_{\theta}(x) - a_{\theta})] = 0$

Optimal bias-robust estimator (OBRE)

$$\frac{1}{n} \sum_{i=1}^n w_b(X_i) (\Lambda_{\theta}(X_i) - a_{\theta}) = 0,$$

with  $w_b(x) = \min\left(1, \frac{b}{\|A(\Lambda_{\theta}(x) - a_{\theta})\|}\right)$ ,  $a_{\theta} = \frac{\int w_b(x) \Lambda_{\theta}(x) dF_{\theta}}{\int w_b(x) dF_{\theta}}$

and  $A = \left(\int (\Lambda_{\theta}(x) - a_{\theta})(\Lambda_{\theta}(x) - a_{\theta})^t w_b(x) dF_{\theta}\right)^{-1}$

## Estimators [contd.]

Estimator

Solution to

Method of moments (MOM)

$$\bar{X} = E_{\theta}X \text{ and } \overline{X^2} = E_{\theta}X^2$$

Minimum distance estimator (CvM)

$$d_{CvM}(\hat{F}_n, F_{\theta}) = \sqrt{\int (\hat{F}_n - F_{\theta})^2 dF_{\theta}} = \min_{\theta}$$

Minimum distance estimator (Kol)

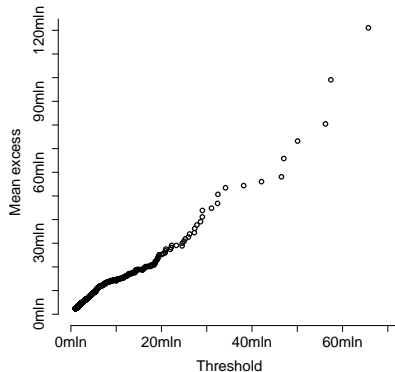
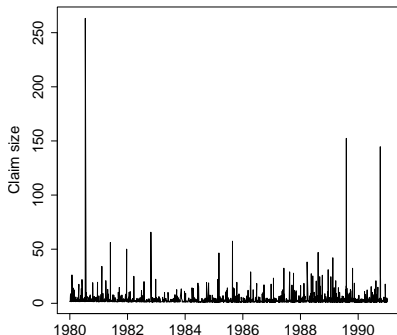
$$d_{Kol}(\hat{F}_n, F_{\theta}) = \sup_{y \in \mathbb{R}} |\hat{F}_n(y) - F_{\theta}(y)| = \min_{\theta}$$

## Danish Fire Claims Data revisited

### Casestudy

Model 1: Exceedances over threshold of 10mln DKK

Model 2: Introduction of new largest loss of 350mln DKK to dataset



2,156 fire insurance claims over 1mln DKK from 1980 to 1990.

## Danish Fire Claims Data revisited

### Model 1: Exceedances over threshold of 10mln DKK

Estimator	Scale parameter		Shape parameter		GES	Quantiles	
	$\beta$	s.e. $\beta$	$\xi$	s.e. $\xi$		99.5%	99.9%
MLE	6.975	1.156	0.497	0.143	$\infty$	181	421
MOM	8.520		0.395		$\infty$	153	309
OBRE ( $b = 10$ )	6.970	1.161	0.494	0.149	10	179	413
OBRE ( $b = 9$ )	6.982	1.164	0.488	0.150	9	176	403
OBRE ( $b = 8$ )	7,032	1.162	0.454	0.150	8	156	341
MDE CvM	7.696	1.382	0.333	0.202	28	112	208

- MLE is efficient but not robust.
- MOM provides a poor fit, the estimator is not asymptotically normal ( $\xi > 1/4$ ).
- OBRE and MDE CvM are relatively efficient and robust. The radius is 5.1% ( $b = 10$ ), 6.4% ( $b = 9$ ), 8.1% ( $b = 8$ ).

## Danish Fire Claims Data revisited

Model 1: Exceedances over threshold of 10mln DKK

Model 2: Introduction of new largest loss of 350mln DKK to dataset

Estimator	$\xi$	Model 1		$\xi$	Model 2		Delta 99.9%- Quantile
		Quantiles			Quantiles		
		99.5%	99.9%		99.5%	99.9%	
MLE	0.497	181	421	0.597	257	690	64%
PWM	0.517	191	455	0.613	266	732	61%
OBRE ( $b = 10$ )	0.494	179	413	0.592	252	672	63%
OBRE ( $b = 9$ )	0.488	176	403	0.571	234	603	50%
OBRE ( $b = 8$ )	0.454	156	341	0.551	218	545	60%
MDE CvM	0.333	112	208	0.370	127	248	19%
MDE Kol	0.457	158	347	0.489	179	410	18%

- McNeil (1996) indicates the sensitivity of the shape parameter to contamination applying ML calculus (in context of pricing XL treaties). Robust estimators, e.g. minimum distance estimators, may stabilize the results.

## Conclusions

- Robust estimation is not a means to downweight large claims and reduce rates or risk indications.
- Rather, robust statistics may help
  - to fit a distribution to the bulk of the data and to identify outliers,
  - shed light on the sensitivity of estimators and provide information for calibration and validation of models,
  - to establish models that react more resilient to deviations from the ideal setup.